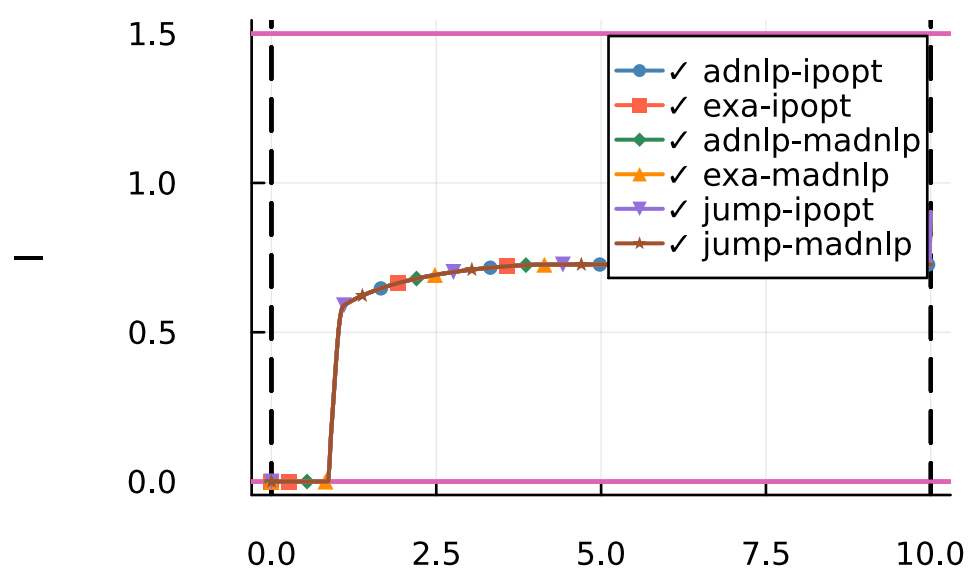
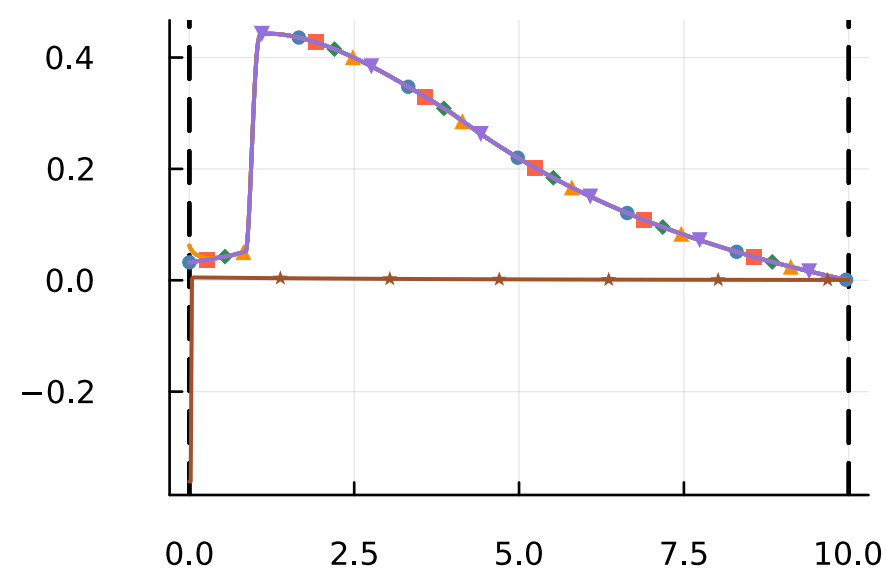


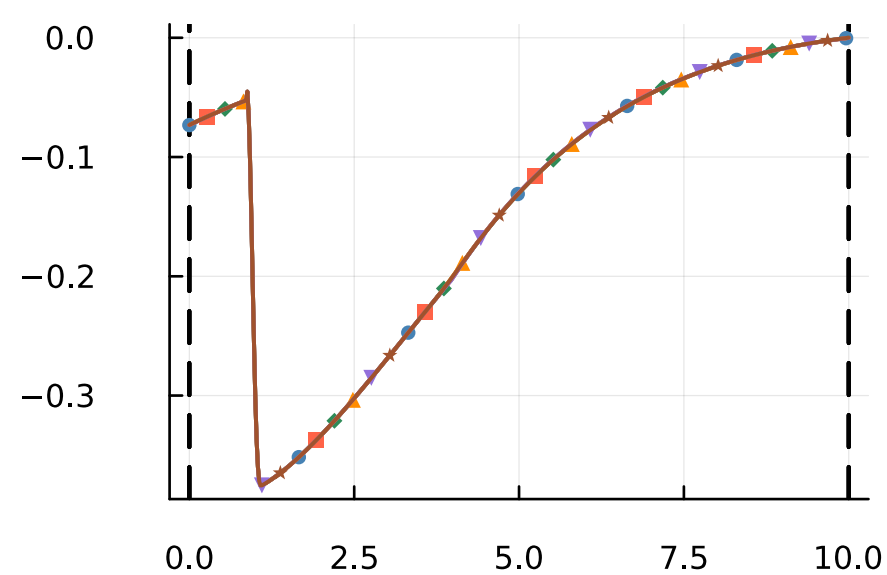
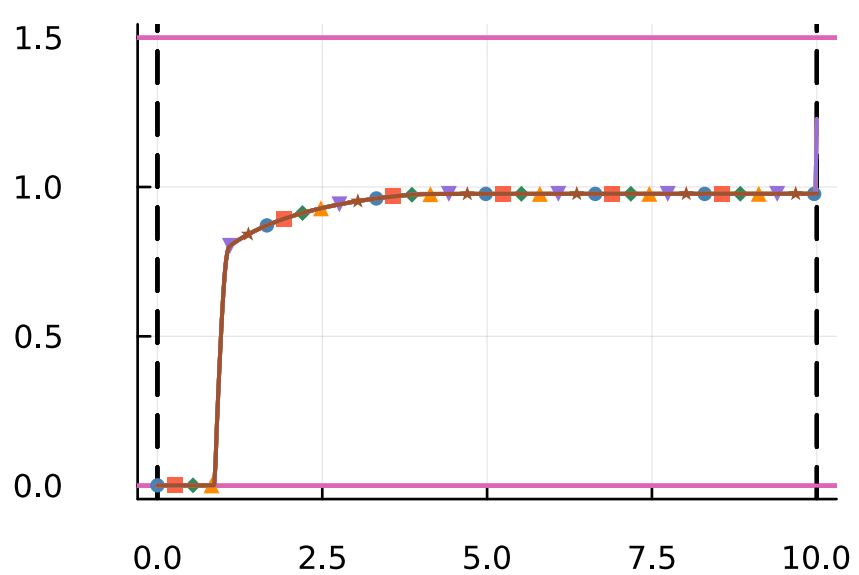
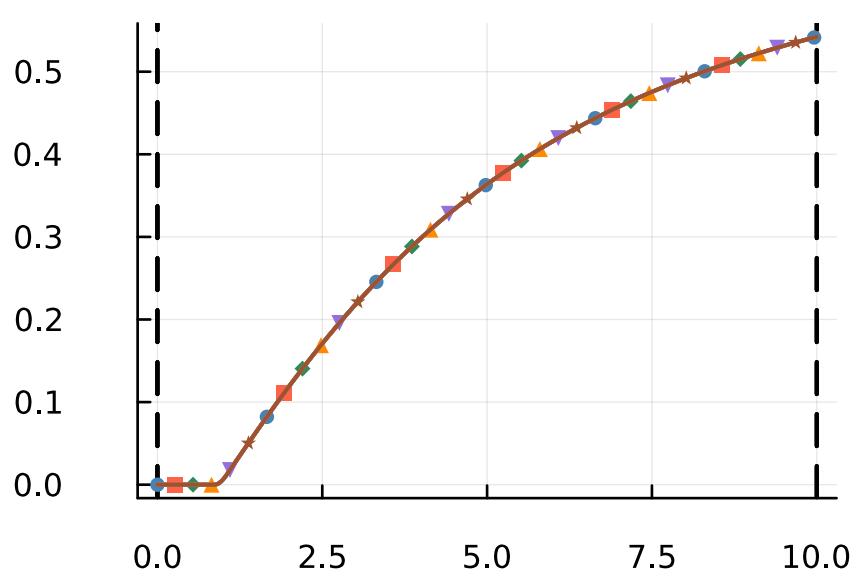
state



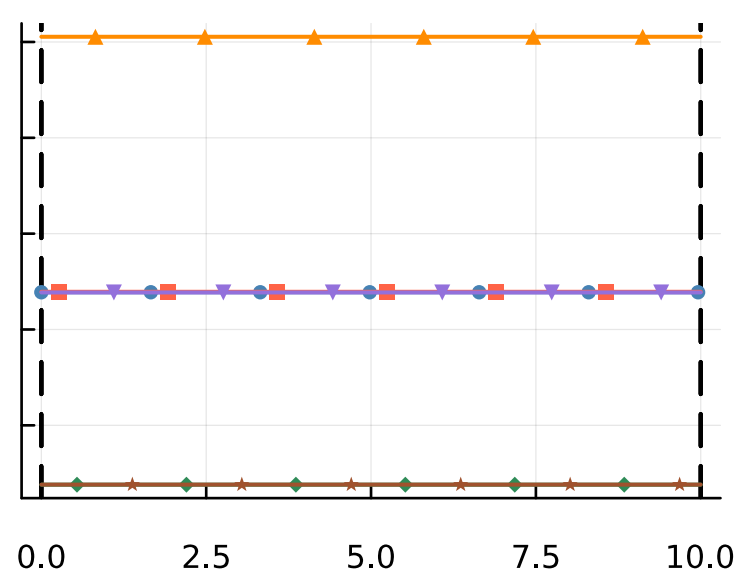
costate



m

 x_3 

-3.614740×10^{-1}
 -3.614760×10^{-1}
 -3.614780×10^{-1}
 -3.614800×10^{-1}
 -3.614820×10^{-1}

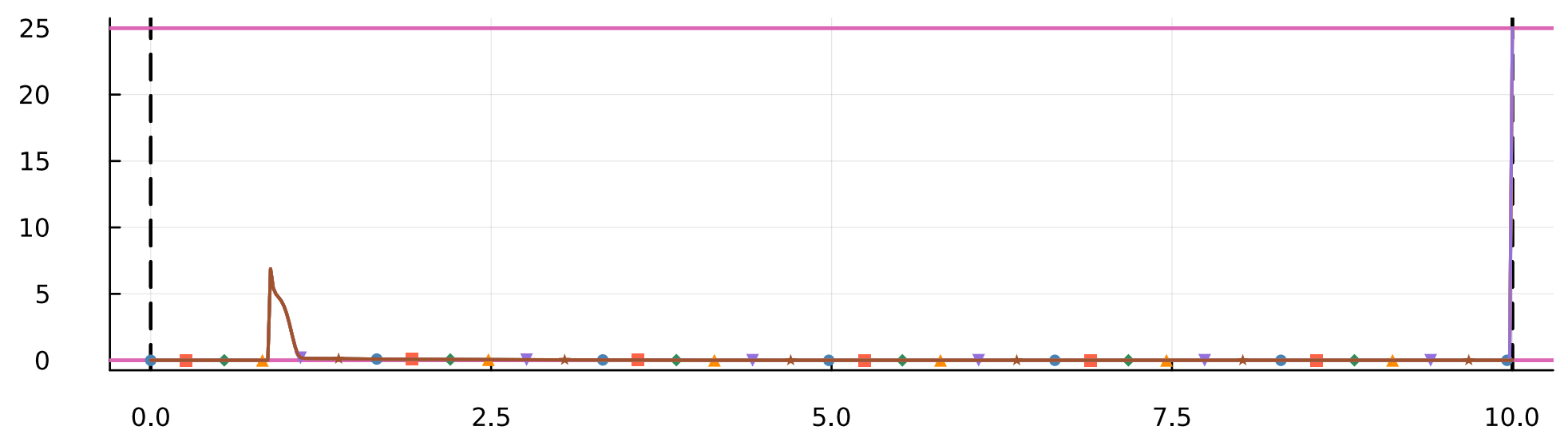


t

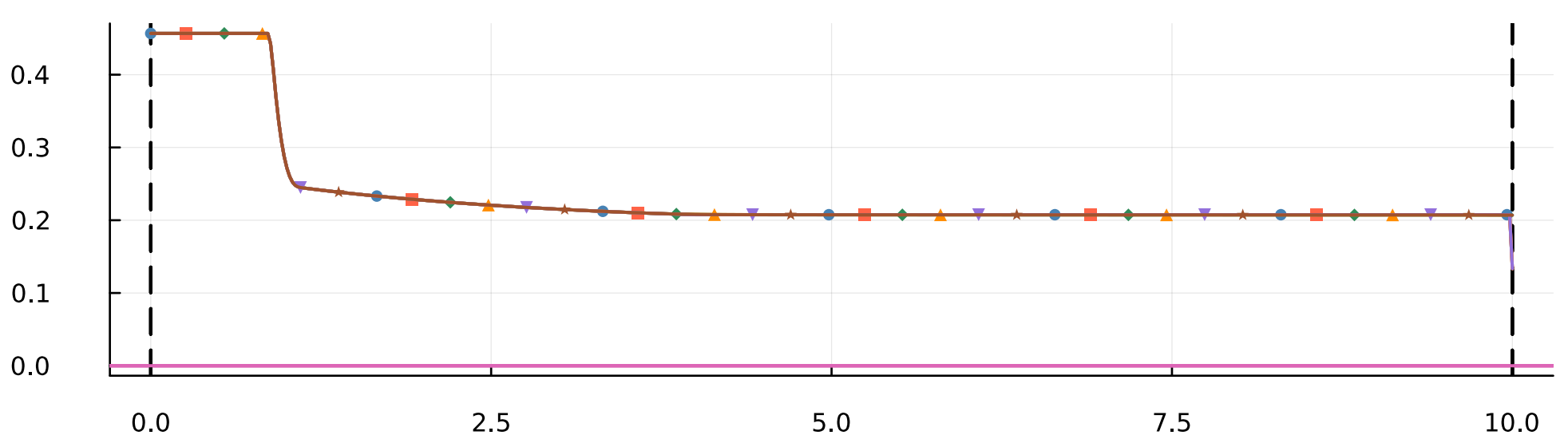
t

control

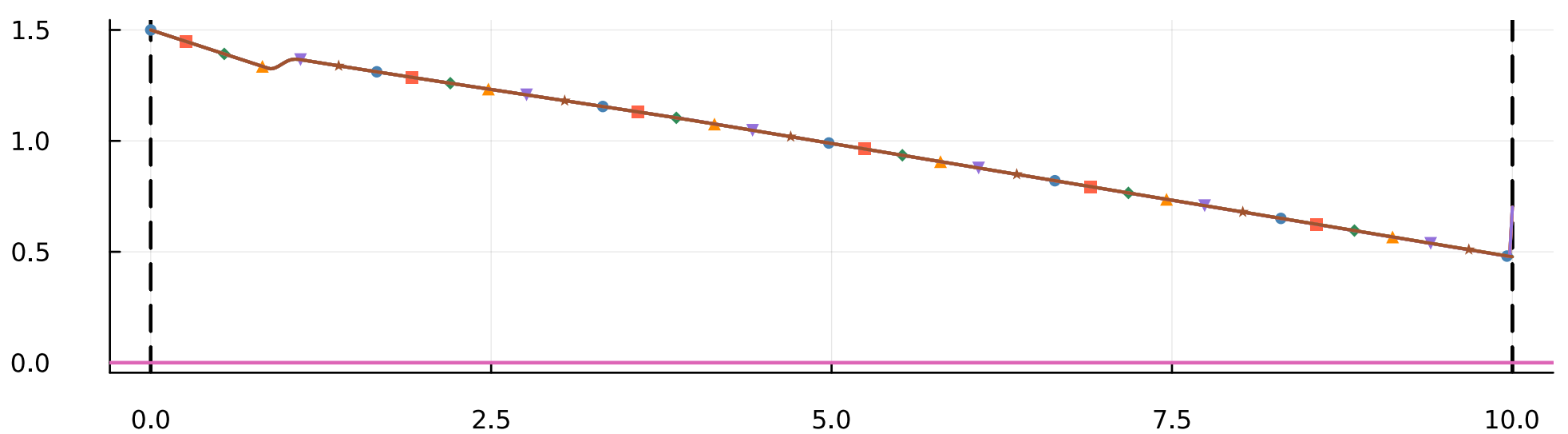
h



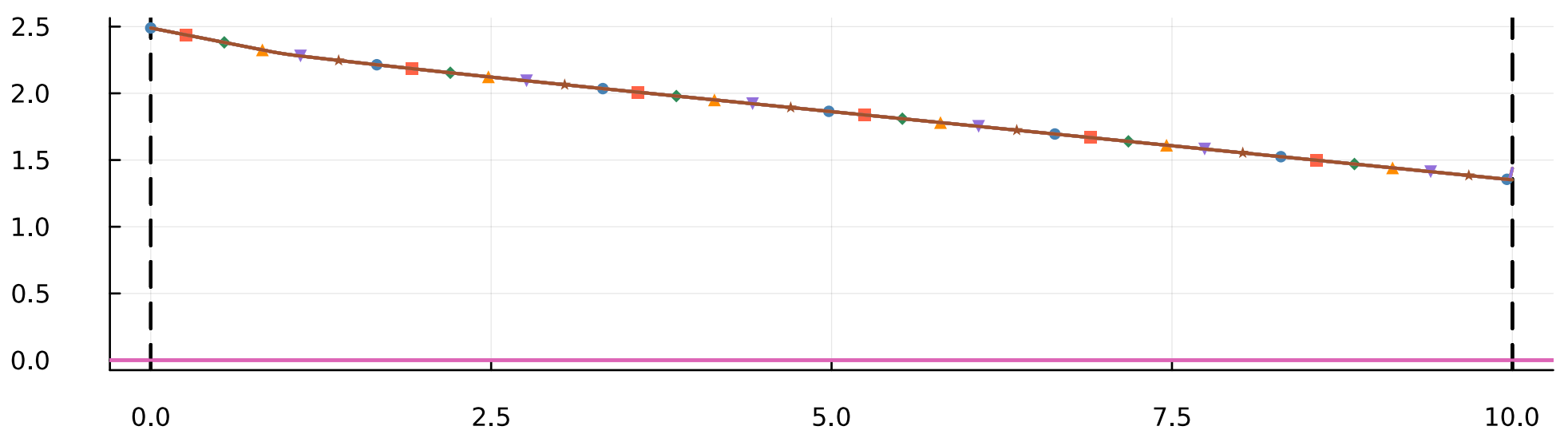
R



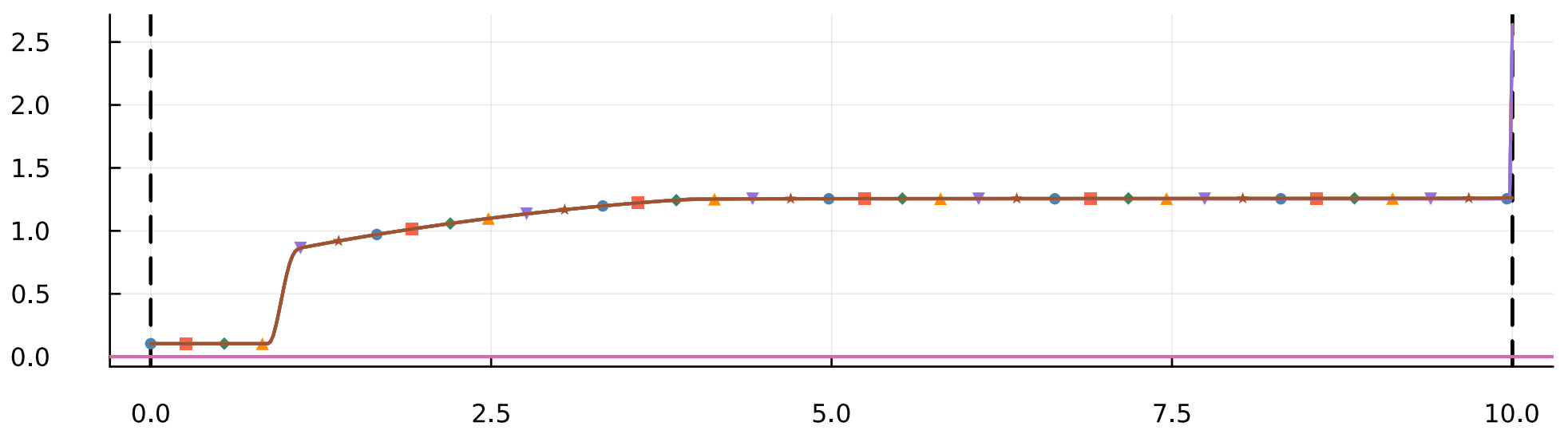
H



U



dUdR



t