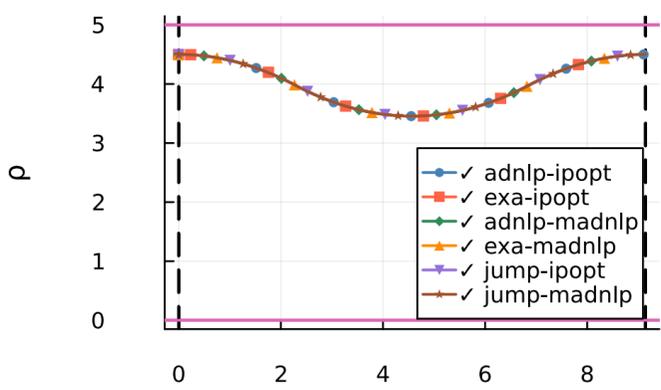
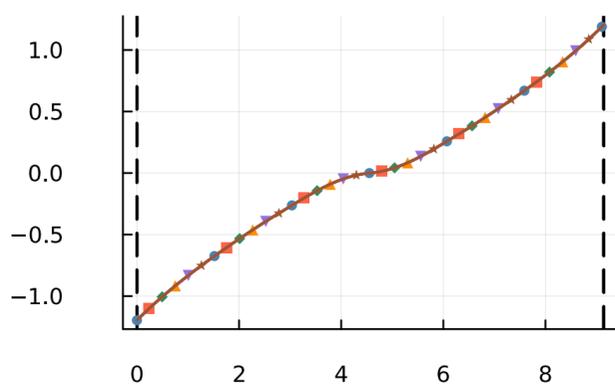
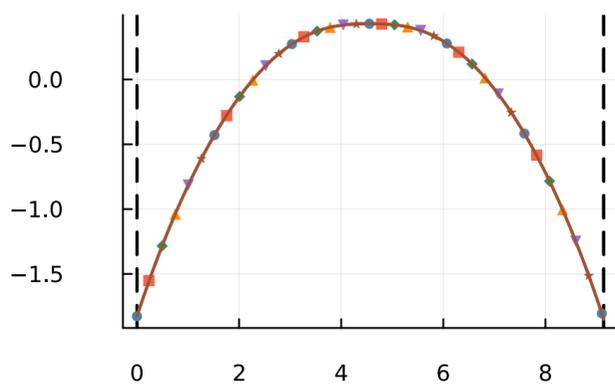
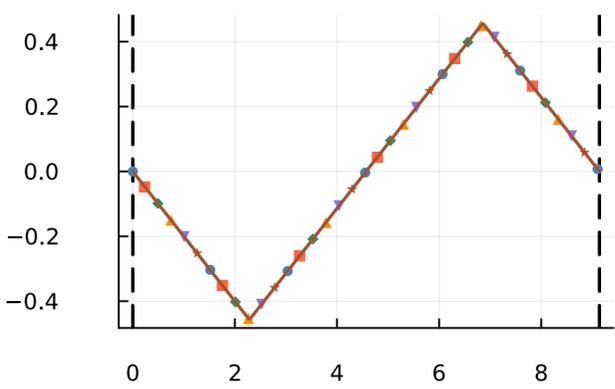
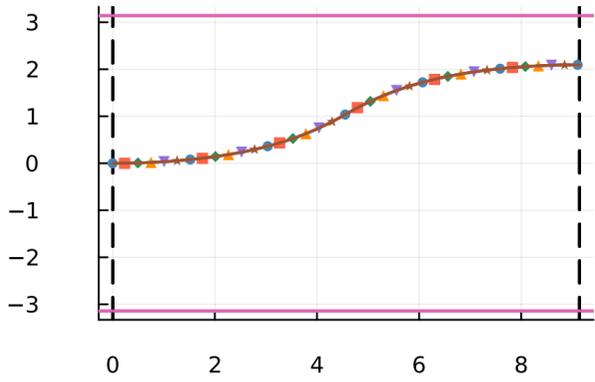


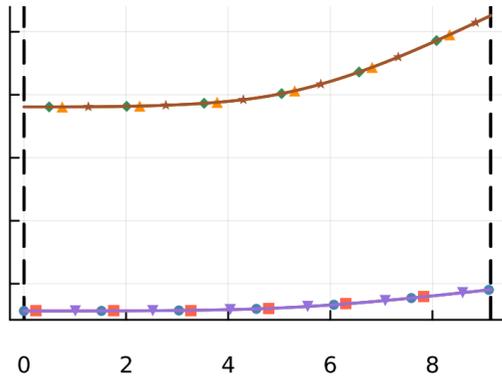
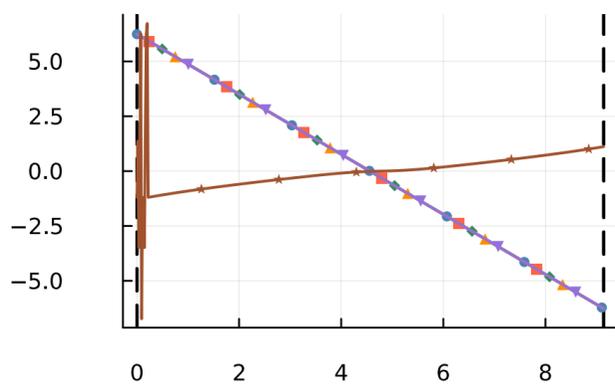
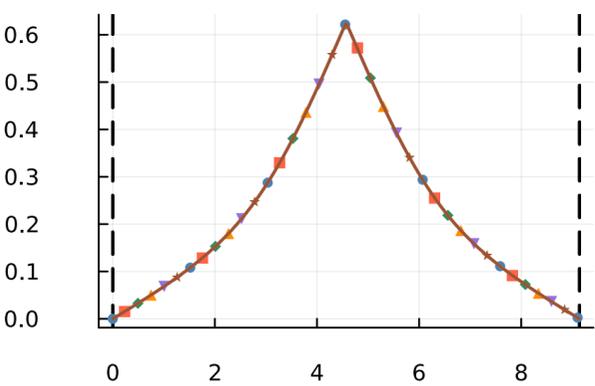
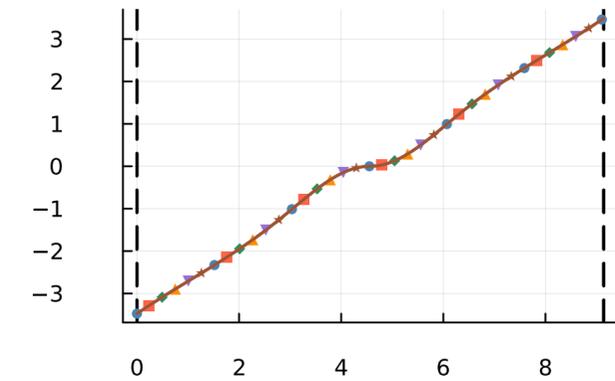
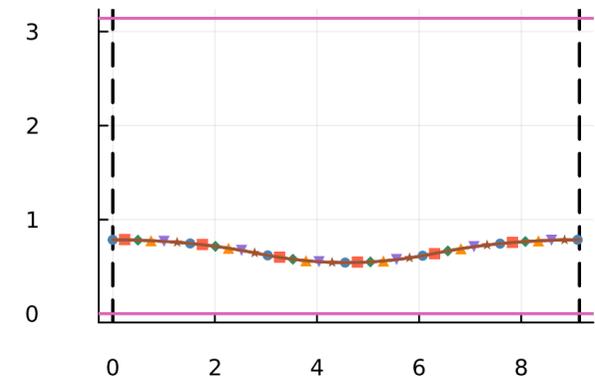
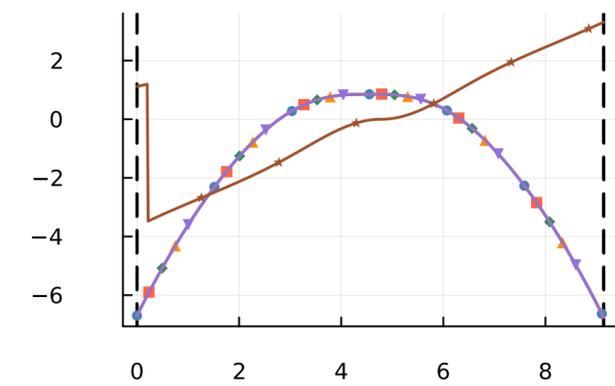
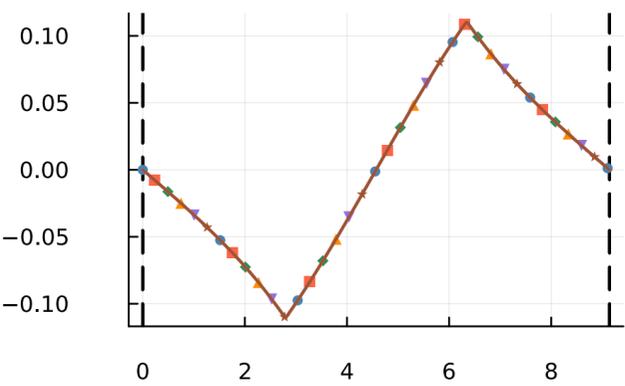
state



costate

 $d\rho$  $\theta$ 

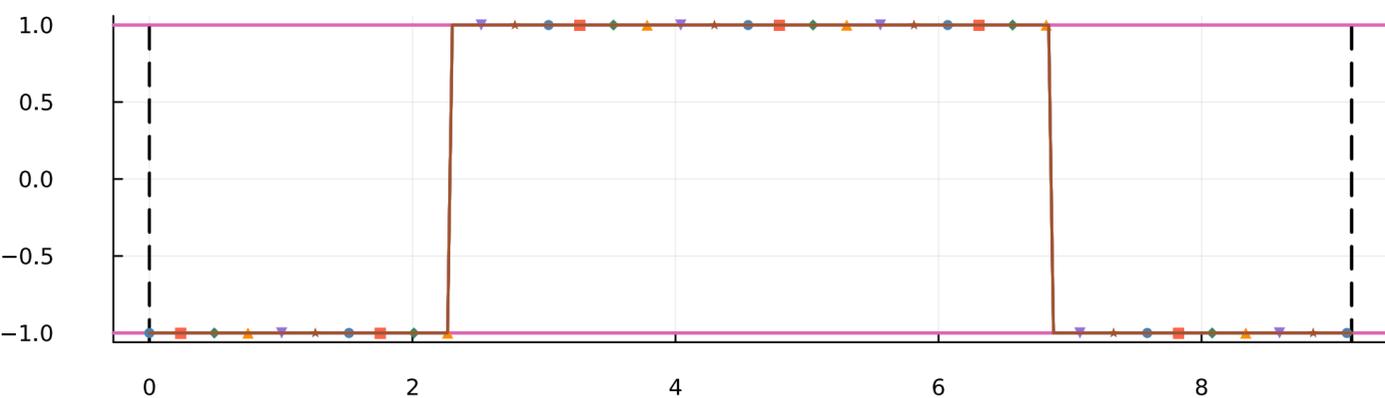
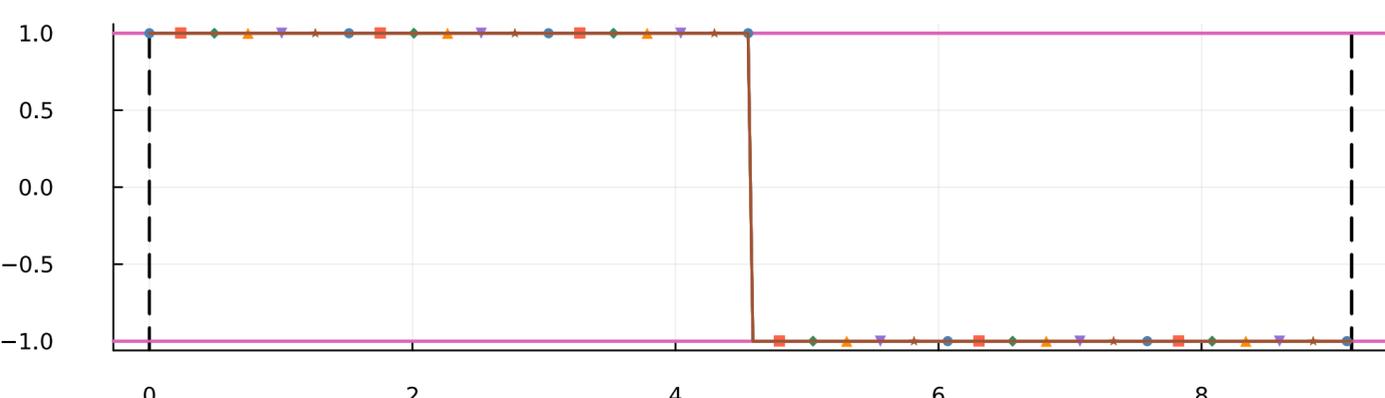
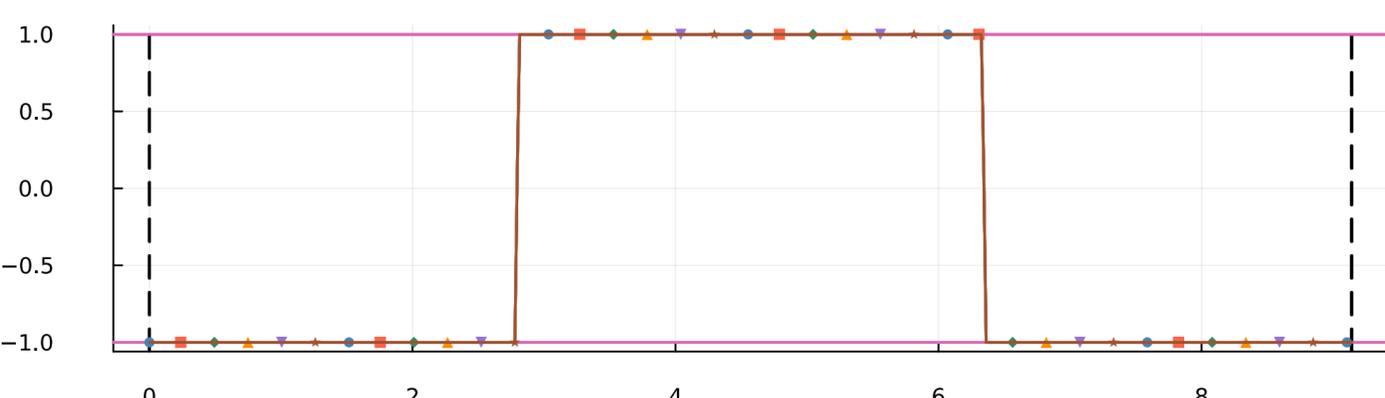
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 $d\theta$  $\phi$  $d\phi$ 

t

t

control

 $u\rho$  $u\theta$  $u\phi$ 

t